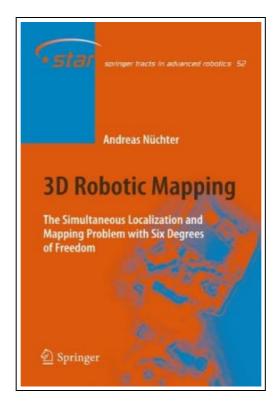
# 3D Robotic Mapping: The Simultaneous Localization and Mapping Problem with Six Degrees of Freedom



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(Matilda Hoeger V)

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