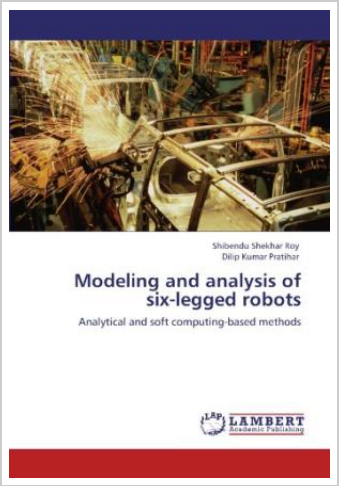

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Modeling and Analysis of Six-Legged Robots

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